

## Assignment 7

$$\begin{aligned}
 1a) \quad x_\mu x_\mu &= x_\mu^1 x_\mu^1 \\
 &= \lambda_{\mu\sigma} x_\sigma \lambda_{\mu\rho} x_\rho \\
 &= \lambda_{\mu\sigma} \lambda_{\mu\rho} x_\sigma x_\rho
 \end{aligned}$$

$$\therefore \delta_{\sigma\rho} = \lambda_{\mu\sigma} \lambda_{\mu\rho}$$

$$= \lambda_{\sigma\mu}^T \lambda_{\mu\rho}$$

$$\therefore 1 = \lambda^T \lambda \text{ or } 1 = \lambda \lambda^T$$

$$b) \quad \lambda \lambda^T = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \gamma & i\beta\gamma \\ 0 & 0 & -i\beta\gamma & \gamma \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \gamma & -i\beta\gamma \\ 0 & 0 & i\beta\gamma & \gamma \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \gamma^2(1-\beta^2) & \gamma^2(-i\beta+i\beta) \\ 0 & 0 & \gamma^2(-i\beta+i\beta) & \gamma^2(-\beta^2+1) \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\therefore \lambda \lambda^T = 1$$

2a) A 4-vector  $M_\mu$  transforms according to  $M'_\mu = \lambda_{\mu\nu} M_\nu$ .

$$\therefore M'_4 = \gamma (M_4 - i\beta M_3)$$

$$\text{if } M = (\vec{x}, o) \Rightarrow o = \gamma(o - i\beta x_3) \\ M' = (\vec{x}', o) = -i\beta \gamma x_3.$$

This is nonsense.  $\therefore (\vec{x}, o)$  is not a 4-vector.

b)  $x_1 = x_1'$

$$x_2 = x_2'$$

$$x_3 = \gamma(x_3' - i\beta x_4')$$

$$x_4 = \gamma(x_4' + i\beta x_3')$$

$$\square \equiv \left( \nabla, \frac{d}{dx_4} \right)$$

Obviously  $\frac{d}{dx_1'} = \frac{d}{dx_1}$

$$\frac{d}{dx_2'} = \frac{d}{dx_2}$$

$$\begin{aligned} \frac{d}{dx_3'} &= \frac{d}{dx_3'} \frac{d}{dx_3} + \frac{d}{dx_3'} \frac{d}{dx_4} \\ &= \gamma \frac{d}{dx_3} + i\beta \gamma \frac{d}{dx_4}. \end{aligned}$$

$$= \lambda_{33} \frac{d}{dx_3} + \lambda_{34} \frac{d}{dx_4}$$

$$\begin{aligned}
 \frac{\partial}{\partial x_4} &= \frac{\partial x_3}{\partial x'_4} \frac{\partial}{\partial x_3} + \frac{\partial x_4}{\partial x'_4} \frac{\partial}{\partial x_4} \\
 &= -i\beta\gamma \frac{\partial}{\partial x_3} + \gamma \frac{\partial}{\partial x_4} \\
 &= \lambda_{43} \frac{\partial}{\partial x_3} + \lambda_{44} \frac{\partial}{\partial x_4}.
 \end{aligned}$$

$$\therefore \square' = \lambda \square$$

Hence  $\square$  is a 4-vector.

c)  $t$  is not a Lorentz invariant since a moving observer measures a time

$$t' = \gamma \left( t - \frac{\beta}{c} x_3 \right) \neq t.$$

d) A tensor satisfies  $T'_{\mu\nu} = \lambda_{\mu\alpha} \lambda_{\nu\beta} T_{\alpha\beta}$

$$\begin{aligned}
 \lambda_{\mu\alpha} \lambda_{\nu\beta} \delta_{\alpha\beta} &= \lambda_{\mu\alpha} \lambda_{\nu\alpha} \\
 &= \delta_{\mu\nu} \quad \text{from #1} \\
 &\equiv \delta'_{\mu\nu}
 \end{aligned}$$

$\therefore \delta_{\mu\nu}$  is a tensor.

$$3) \quad \frac{\partial F_{\mu\nu}}{\partial x_\nu} = \frac{4\pi}{c} J_\mu$$

$$\text{let } \mu=1 \Rightarrow \frac{\partial F_{1\nu}}{\partial x_\nu} = \frac{4\pi}{c} J_1$$

$$\frac{\partial F_{11}}{\partial x_1} + \frac{\partial F_{12}}{\partial x_2} + \frac{\partial F_{13}}{\partial x_3} + \frac{\partial F_{14}}{\partial x_4} = \frac{4\pi}{c} J_1$$

$$0 + \frac{\partial B_3}{\partial x_2} - \frac{\partial B_2}{\partial x_3} + \frac{\partial(-iE_1)}{\partial(\text{ict})} = \frac{4\pi}{c} J_1$$

$$(\nabla \times \vec{B})_1 - \frac{1}{c} \frac{\partial E_1}{\partial t} = \frac{4\pi}{c} J_1$$

Combining this result with eqns. resulting  
when  $\mu=2, 3$  gives:

$$\nabla \times \vec{B} - \frac{1}{c} \frac{\partial \vec{E}}{\partial t} = \frac{4\pi}{c} \vec{J}.$$

$$\text{let } \mu=4 \Rightarrow \frac{\partial F_{4\nu}}{\partial x_\nu} = \frac{4\pi}{c} J_4$$

$$\frac{\partial F_{41}}{\partial x_1} + \frac{\partial F_{42}}{\partial x_2} + \frac{\partial F_{43}}{\partial x_3} + \frac{\partial F_{44}}{\partial x_4} = \frac{4\pi}{c} J_4.$$

$$i \frac{\partial E_1}{\partial x_1} + i \frac{\partial E_2}{\partial x_2} + i \frac{\partial E_3}{\partial x_3} = \frac{4\pi}{c} i c p.$$

$$\therefore \nabla \cdot \vec{E} = 4\pi \rho.$$

4a) We need to show  $T'_{\mu\nu} = \lambda_{\mu\alpha} \lambda_{\nu\beta} T_{\alpha\beta}$ .

$$\lambda_{\mu\alpha} \lambda_{\nu\beta} T_{\alpha\beta} = \lambda_{\mu\alpha} \lambda_{\nu\beta} \frac{1}{4\pi} [F_{\alpha\sigma} F_{\sigma\beta} + \frac{1}{4} \delta_{\alpha\beta} F_{\lambda\rho} F_{\lambda\rho}]$$

$$= \frac{1}{4\pi} \left\{ \lambda_{\mu\alpha} \lambda_{\sigma\gamma} F_{\alpha\sigma} \lambda_{\gamma\beta} \lambda_{\nu\beta} F_{\sigma\beta} \right.$$

$$\left. + \frac{1}{4} \lambda_{\mu\alpha} \lambda_{\nu\beta} \delta_{\alpha\beta} \lambda_{\lambda\lambda} \lambda_{\rho\rho} F_{\lambda\rho} \lambda_{\lambda\lambda} \lambda_{\rho\rho} F_{\lambda\rho} \right\}$$

where we used  $\lambda_{\sigma\gamma} \lambda_{\gamma\beta} = 1$  (See #1)

$$= \frac{1}{4\pi} \left\{ F'_{\mu\sigma} F_{\sigma\nu} + \frac{1}{4} \delta'_{\mu\nu} F_{\lambda\rho} F_{\lambda\rho} \right\}$$

since  $F_{\mu\nu}, \delta'_{\mu\nu}$  are tensors

$\therefore \lambda_{\mu\alpha} \lambda_{\nu\beta} T_{\alpha\beta} = T'_{\mu\nu} \Rightarrow T_{\mu\nu}$  is a tensor.

$$b) T_{11} = \frac{1}{4\pi} [F_{16} F_{61} + \frac{1}{4} \delta_{11} F_{\lambda\rho} F_{\lambda\rho}]$$

$$= \frac{1}{4\pi} [0 + B_3 (-B_3) + (-B_2) B_2 + (-iE_1) iE_1]$$

$$+ \frac{1}{4} \left( B_3^2 + B_2^2 + B_1^2 - E_1^2 - E_2^2 - E_3^2 \right) 2 ]$$

$$= \frac{1}{4\pi} \left[ -B_3^2 - B_2^2 + E_1^2 + \frac{1}{2} (\vec{B}^2 - \vec{E}^2) \right]$$

$$\therefore T_{11} = \frac{1}{4\pi} \left[ B_1^2 + E_1^2 - \frac{1}{2} (\vec{B}^2 + \vec{E}^2) \right]$$

$$\begin{aligned}
T_{41} &= \frac{1}{4\pi} \left[ F_{4\sigma} F_{\sigma 1} + \frac{1}{4} \delta_{41} F_{\lambda\rho} F_{\lambda\rho} \right] \\
&= \frac{1}{4\pi} \left[ iE_1 o + iE_2 (-B_3) + iE_3 B_2 + o iE_1 \right] \\
&= \frac{-i}{4\pi} (E_2 B_3 - E_3 B_2) \\
\therefore T_{41} &= \frac{-i}{4\pi} (\vec{E} \times \vec{B}), \\
T_{44} &= \frac{1}{4\pi} \left[ F_{4\sigma} F_{\sigma 4} + \frac{1}{4} \delta_{44} F_{\lambda\rho} F_{\lambda\rho} \right] \\
&= \frac{1}{4\pi} \left[ iE_1 (-iE_1) + iE_2 (-iE_2) + iE_3 (-iE_3) + o \right. \\
&\quad \left. + \frac{1}{2} (\vec{B}^2 - \vec{E}^2) \right] \\
&= \frac{1}{4\pi} \left[ \vec{E}^2 + \frac{1}{2} (\vec{B}^2 - \vec{E}^2) \right] \\
\therefore T_{44} &= \frac{1}{8\pi} (\vec{E}^2 + \vec{B}^2)
\end{aligned}$$

$$5a) K' = (\rho_0 \vec{E}', 0)$$

$$b) K' = \lambda K$$

or  $K = \lambda^T K'$

$$= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \gamma & -i\beta\gamma \\ 0 & 0 & i\beta\gamma & \gamma \end{pmatrix} \begin{pmatrix} \rho_0 E'_1 \\ \rho_0 E'_2 \\ \rho_0 E'_3 \\ 0 \end{pmatrix}$$

$$K = \begin{pmatrix} \rho_0 E'_1 \\ \rho_0 E'_2 \\ \gamma \rho_0 E'_3 \\ i\beta \gamma \rho_0 E'_3 \end{pmatrix}$$

$$c) E'_1 = \gamma(E_1 - \beta B_2) \quad B'_1 = \gamma(B_1 + \beta E_2)$$

$$E'_2 = \gamma(E_2 + \beta B_1) \quad B'_2 = \gamma(B_2 - \beta E_1)$$

$$E'_3 = E_3 \quad B'_3 = B_3$$

d)  $J$  is a 4-vector.

$$\therefore J = \lambda^T J' \quad \text{where } J' = (0, i\rho_0)$$

$$J_4 = \lambda_{44}^T J'_4$$

$$i\rho_0 = \lambda_{44}^T i\rho_0$$

$$\therefore \rho = \gamma \rho_0$$

$$e) K_1 = \rho_0 E'_1$$

$$= \frac{\rho}{\gamma} \gamma (E_1 - \beta B_z)$$

$$= \rho (E_1 - \beta B_z)$$

$$\text{Now } \vec{\beta} = (0, 0, \frac{u}{c})$$

$$\therefore K_1 = \rho [E_1 + (\vec{\beta} \times \vec{B})_1]$$

$$\text{Similarly } K_2 = \rho [E_2 + (\vec{\beta} \times \vec{B})_2]$$

$$K_3 = \gamma \rho_0 E'_3$$

$$= \gamma \frac{\rho}{\gamma} E_3$$

$$= \rho [E_3 + (\vec{\beta} \times \vec{B})_3]$$

$$\therefore \text{Lorentz force density } \vec{K} = \rho (\vec{E} + \vec{\beta} \times \vec{B}).$$