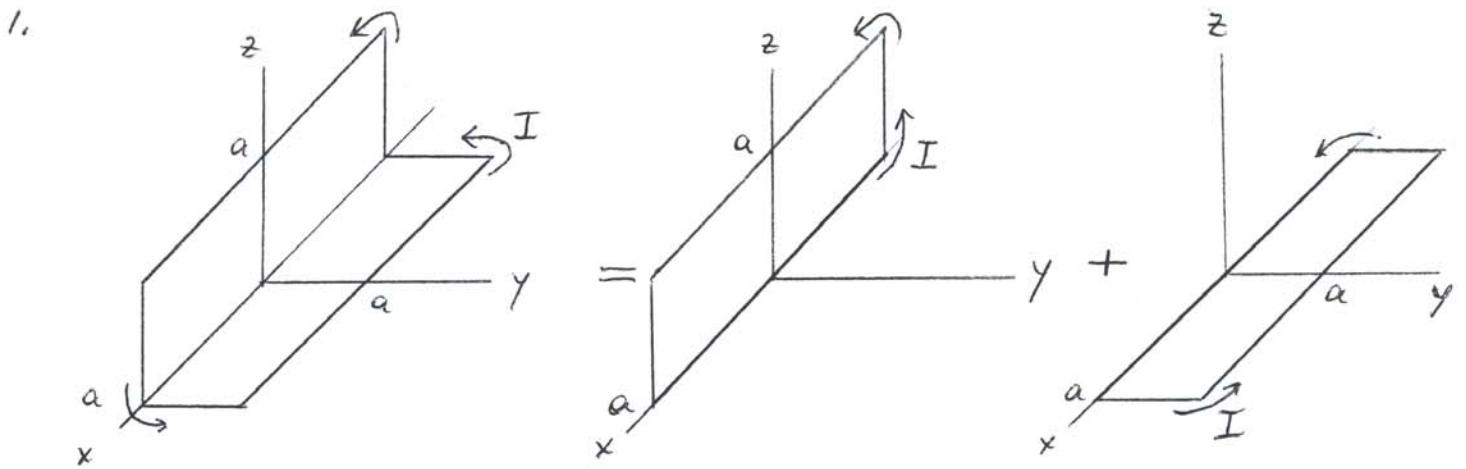


Assignment 8



$$\vec{m} = \frac{I 2a^2}{c} \hat{y} + \frac{I 2a^2}{c} \hat{z}$$

$$= \frac{2 I a^2}{c} (\hat{y} + \hat{z})$$

2a) $\vec{A} = \frac{\vec{m} \times \vec{r}}{r^3}$

$$\vec{B} = \nabla \times \vec{A}$$

$$= \nabla \times \left(\vec{m} \times \frac{\vec{r}}{r^3} \right)$$

$$= -(\vec{m} \cdot \nabla) \left(\frac{\vec{r}}{r^3} \right) + \vec{m} \underbrace{\left(\nabla \cdot \left(\frac{\vec{r}}{r^3} \right) \right)}_{=0} \quad \text{class exercise}$$

$$\vec{B}_x = -(\vec{m} \cdot \nabla) \left(\frac{x}{r^3} \right)$$

$$= - \left[m_x \frac{\partial}{\partial x} + m_y \frac{\partial}{\partial y} + m_z \frac{\partial}{\partial z} \right] \left(\frac{x}{r^3} \right)$$

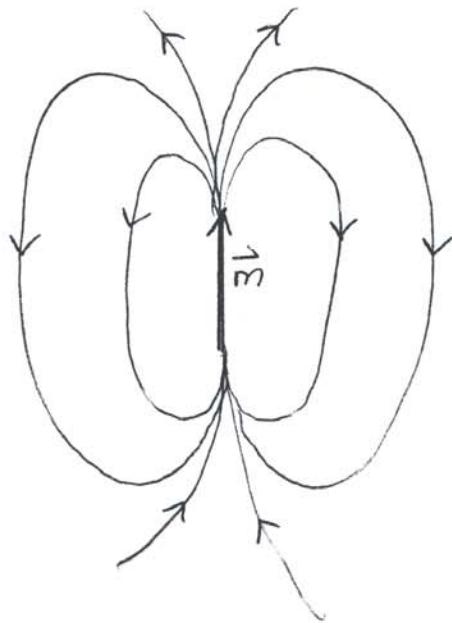
$$= - \left\{ m_x \frac{1}{r^3} + x \left[m_x \frac{\partial r^{-3}}{\partial x} + m_y \frac{\partial r^{-3}}{\partial y} + m_z \frac{\partial r^{-3}}{\partial z} \right] \right\}$$

$$= - \frac{m_x}{r^3} + 3x \left[\frac{m_x x}{r^5} + \frac{m_y y}{r^5} + \frac{m_z z}{r^5} \right] \}$$

$$B_x = -\frac{m_x}{r^3} + 3 \times \frac{(\vec{m} \cdot \hat{r})}{r^5}$$

$$\therefore \vec{B} = -\frac{\vec{m}}{r^3} + 3 \frac{\hat{r} (\vec{m} \cdot \hat{r})}{r^5}$$

b).



Magnetic field lines of mag. dipole are the same as electric field lines of electric dipole

$$3a) \text{ Current } I = e \frac{v}{2\pi r}$$

$$\text{Magnetic dipole moment } \mu = \frac{IA}{c}$$

$$= \frac{ev}{2\pi r} \frac{\pi r^2}{c}$$

$$= \frac{e}{2mc} mv r$$

$$\therefore \mu = \frac{eL}{2mc}$$

$$b) \text{ Torque} = \frac{d\vec{L}}{dt}$$

$$\frac{d\vec{L}}{dt} = \vec{\mu} \times \vec{B}.$$

$$\frac{d\vec{\mu}}{dt} = \gamma \vec{\mu} \times \vec{B} \quad \text{using } \vec{\mu} = \gamma \vec{L}.$$

$$= \gamma (\mu_y B, -\mu_x B, 0) \quad \text{since } \vec{B} = (0, 0, B).$$

$$\frac{d\mu_z}{dt} = 0 \implies \mu_z = \mu_z(0) = \text{constant (zero in our case)}$$

$$\frac{d\mu_y}{dt} = -\gamma B \mu_x \quad (1)$$

$$\frac{d\mu_x}{dt} = \gamma B \mu_y \quad (2)$$

$$(1) + (2) \implies \frac{d^2}{dt^2} \begin{Bmatrix} \mu_x \\ \mu_y \end{Bmatrix} = -(\gamma B)^2 \begin{Bmatrix} \mu_x \\ \mu_y \end{Bmatrix}$$

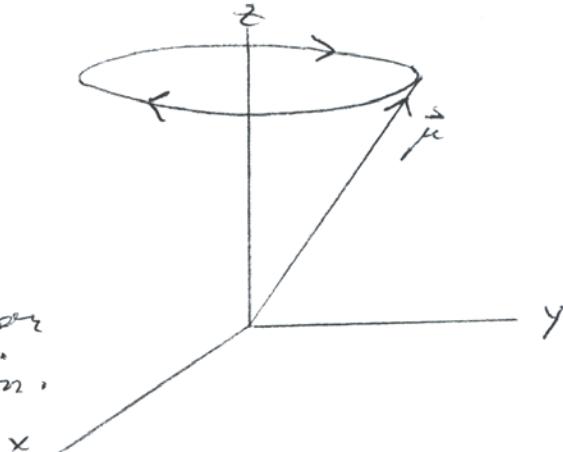
$$\begin{aligned} \mu_x &= A \cos \gamma B t + B \sin \gamma B t && \text{where } A, B, C + D \text{ are} \\ \mu_y &= C \cos \gamma B t + D \sin \gamma B t && \text{constants.} \end{aligned}$$

Using initial condns. $\mu_x(0) = \mu_0$ we get:
 $\mu_y(0) = 0$

$$\mu_x = \mu_0 \cos \gamma B t$$

$$\mu_y = -\mu_0 \sin \gamma B t.$$

$\vec{\mu}$ precesses about \hat{z} or magnetic field direction.



4a) \vec{H} is found using $\oint \vec{H} \cdot d\vec{\ell} = \frac{4\pi}{c} I_{\text{enclosed}}$ by loops.

By symmetry $\vec{H} = H(r)\hat{\phi}$.

Consider a loop of radius r centered about conductor axis.

$$r < a \quad H \cdot 2\pi r = \frac{4\pi}{c} I \quad \frac{\pi r^2}{\pi a^2}$$

$$\vec{H} = \frac{2I}{ca^2} r \hat{\phi}$$

$$b > r > a \quad \vec{H} = \frac{2I}{rc} \hat{\phi}$$

$$r > b \quad \vec{H} = 0.$$

Magnetization $\vec{M} = \chi_m \vec{H}$.

$$r < a \quad \vec{M} = 0$$

$$b > r > a \quad \vec{M} = \frac{2I}{rc} \chi_m \hat{\phi}$$

$$r > b \quad \vec{M} = 0$$

$$\vec{B} = \vec{H} + 4\pi \vec{M}$$

$$r < a \quad \vec{B} = \frac{2I}{ca^2} r \hat{\phi}$$

$$b > r > a \quad \vec{B} = (1 + 4\pi \chi_m) \frac{2I}{rc} \hat{\phi}$$

$$r > b \quad \vec{B} = 0.$$

b) Volume bound current density

$$\vec{J}_b = c (\nabla \times \vec{M})$$

$$= c \frac{1}{r} \frac{\partial}{\partial r} (r M_\phi) \hat{z}$$

$$\vec{J}_b = 0$$

Surface bound current density

$$\vec{K}_b = c (\vec{M} \times \hat{n}) \quad \hat{n} = \text{normal to surface}$$

$$\vec{K}_b(r=a) = c (\vec{M} \times (-\hat{r}))$$

$$= c \frac{2I}{ac} \chi_m \hat{\phi} \times (-\hat{r})$$

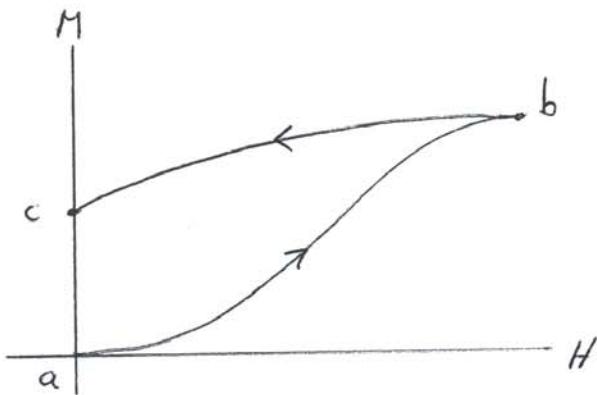
$$= \frac{2I\chi_m}{a} \hat{z}.$$

$$\vec{K}_b(r=b) = c (\vec{M} \times \hat{r})$$

$$= c \frac{2I}{bc} \chi_m \hat{\phi} \times \hat{r}.$$

$$= - \frac{2I\chi_m}{b} \hat{z}.$$

5-



a = begin with chunk of unmagnetized iron.

b = magnetization is maximum when H is max.

c = permanent magnet i.e. $M \neq 0$ with $H = 0$.